

- [Regan Robertson](#) Mod • [15 days ago](#)

Good Morning,

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[Stuart Card](#) • [15 days ago](#)

One idea with which we have been toying is running x86, ARM & RISC-V processors in parallel: while this won't save us from bugs at the source code (or higher) level, it should help with compiler and below (including CPU specific hardware vulnerabilities).

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[Douglas Schafer](#) Stuart Card • [15 days ago](#)

Hey Stu, kind of like popcorn-Linux idea?

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■ [Stuart Card](#) [Douglas Schafer](#) • [15 days ago](#)

"kind of" like their HEXO, yes, details of our approach as yet TBD. :-)

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■ [Ryan Craven](#) [Douglas Schafer](#) • [15 days ago](#)

+1 for mention of popcorn. Popcorn is more general-purpose while the stuff in my talk is geared to CPS.

Link to learn more about separate Popcorn topic: <http://www.popcornlinux.org...>

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■ [Ryan Craven](#) [Stuart Card](#) • [15 days ago](#)

It could still help with higher bugs. Yes, the bug would be present in all architectures, but the input the attacker is forced to craft to exploit that bug is different across those replicas. Depends on what the goal is.

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[Jerry Dussault](#) [Stuart Card](#) • [15 days ago](#) • edited

How would you detect that the running systems have diverged, and determine which one has been compromised? Very interesting to think about!

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[Ryan Craven](#) [Jerry Dussault](#) • [15 days ago](#)

You need watchdog timers, or some form of an orchestration system. Many existing fault tolerance / hot backup systems already have methods for doing this. Another nice synergy with integrating these techniques into existing fault tolerant systems.

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[Stuart Card](#) [Jerry Dussault](#) • 15 days ago

Minimum of 3 for simple voting. With only 2, I don't see how to do it in real time, except when one exceeds fixed bounds on allowed output values.

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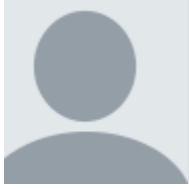
[Ryan Craven](#) [Stuart Card](#) • 15 days ago

One potential issue with comparison. If you're doing general-purpose computing it could get quite a bit more complex. i.e., what are the various "equivalence points"? that depends on the process being executed and you have to extract some structure from it. You'd also have to define some cut-off time (e.g., what if one of your variants is correct, but just takes longer? that's not an attack but just a slow replica).

CPS makes this easier because we have the periodic scan cycle happening ad infinitum. The cycle also has to meet real-time deadlines that are set by the physical system requirements. That gives good structure for comparison.

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[Jason H Li](#) • 15 days ago • edited

slide 11 - I would say a good manager / policy engine is needed to coordinate and manage these in mission / platform context. For defeating these common node failures.

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[Renato Levy](#) • 15 days ago

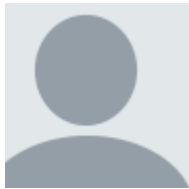
How do you figure out that you are owned. A good attack would mask this

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[Jason H Li](#) [Renato Levy](#) • 15 days ago

This goes back to something we know/are but the bad guys don't know / are not. IMHO.

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[Ryan Craven](#) Renato Levy • 15 days ago

The diversification is key to discovering this. In the example in the slides, if we had run C0 by itself and it gets owned and we never know it because it's still providing inputs on time (we have no idea they're attacker-controlled). but by having the diverse replicas, we infer that someone has been owned when we see non-uniform crashes happen across the replicas.

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[Jason H Li](#) • 15 days ago

The inertia is a boon allowing us to monitor and check. Like the idea of synergizing with fault tolerance ideas. Slides 17 and 18 are very enlightening. Would love to see some of these happen in real platforms, in some practical holistic manner, well tested and orchestrated in context.

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[Ryan Craven](#) Jason H Li • 15 days ago

Thanks Jason! That's what we're working toward. Getting into real platforms.

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[Jerry Dussault](#) • [15 days ago](#)

Thanks Dr. Craven, nice presentation!

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